

New Infinite Family of Regular Edge-Isoperimetric Graphs

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Abstract

We introduce a new infinite family of regular graphs admitting nested solutions in the edge-isoperimetric problem for all their Cartesian powers. The obtained results include as special cases most of previously known results in this area.

1 Introduction

Let $G = (V_G, E_G)$ be a graph and $A, B \subseteq V_G$. Denote

$$\begin{aligned} I_G(A, B) &= \{(u, v) \in E_G \mid u \in A, v \in B\}, \\ I_G(A) &= I_G(A, A), \\ I_G(m) &= \max_{A \subseteq V_G, |A|=m} |I_G(A)|. \end{aligned}$$

We will often omit the index G . Our subject is the following version of the *edge-isoperimetric problem* (EIP): for a fixed m , $1 \leq m \leq |V_G|$, find a set $A \subseteq V_G$ such that $|A| = m$ and $|I(A)| = I(m)$. We call such a set A *optimal*. This problem is known to be NP-complete in general and has many applications in various fields of knowledge, see survey [2].

We restrict ourselves to graphs representable as Cartesian products of other graphs. Given two graphs $G = (V_G, E_G)$ and $H = (V_H, E_H)$, their *Cartesian product* is defined as a graph $G \times H$ with the vertex-set $V_G \times V_H$ whose two vertices (x, y) and (u, v) are adjacent iff either $x = u$ and $(y, v) \in E_H$, or $(x, u) \in E_G$ and $y = v$. The graph $G^n = G \times G \times \dots \times G$ (n times) is called the n^{th} *Cartesian power* of G .

A particular interest in study of EIP is the case when there exists a total order \mathcal{O} on the vertex set of graphs in question such that for every m the initial segment of this order of size m is an optimal set. Such order \mathcal{O} is called *optimal order*. There exist graphs such that their Cartesian powers do not admit optimal orders. For example, it is known that there does not exist optimal orders for the second and higher powers of cycles of length p for $p > 5$ [6]. However, existence of a nested structure of solutions (that is, an optimal order) is an important graph property, because it provides as an immediate consequence solutions to many applied problems. Among such problems are the cutwidth, wirelength, and bisection width problems, construction of good k -partitioning of graphs and their embedding to some other graphs [2]. This stimulates the study of graphs which admit optimal orders for all their Cartesian powers. We call such graphs *edge-isoperimetric*.

The EIP for the Cartesian powers of a graph G has been well intensively studied for various graphs, see survey [2]. To summarize some of these results and present our new one we need to define the *lexicographic order* on a set of n -tuples with integer entries. For that we say that (x_1, \dots, x_n) is greater than (y_1, \dots, y_n) iff there exists an index i , $1 \leq i \leq n$, such that $x_j = y_j$ for $1 \leq j < i$ and $x_i > y_i$. It turns out that just a few different optimal orders are discovered for the EIPs. Some of them are proved to work just for a few graphs [2, 4]. This leaves the lexicographic order to work in most of known cases. In large this is due to the following result called in [1] *local-global principle*.

Theorem 1 (Ahlswede, Cai [1]) *If lexicographic order is optimal for $G \times G$ then it is optimal for G^n for any $n \geq 3$.*

The main difficulty in applying the local-global principle to a given graph G is to establish the optimality of the lexicographic order for $G \times G$. For this, however, no general methods have been developed so far. At this state of research a solution of the EIP on $G \times G$ for any other concrete graph G would be interesting and useful for developing more general methods. It seems difficult to characterize all graphs for whose all Cartesian powers the lexicographic order is optimal. Examples include graphs studied in [1, 3, 8, 9]. However, we believe to the following conjecture.

Conjecture 1 *If lexicographic order is optimal for $G \times G$ then G is regular.*

All graphs studied in the above mentioned papers [1, 3, 8, 9] are regular. In the light of this conjecture we emphasize on Cartesian powers of regular graphs. It is more convenient to work not directly with graphs, but with their numeric characteristic δ_G that we call δ -sequence. For a graph $G = (V, E)$ denote

$$\begin{aligned}\delta(m) &= I(m) - I(m-1), \text{ with } \delta(1) = 0, \\ \delta_G &= (\delta(1), \delta(2), \dots, \delta(|V|)).\end{aligned}$$

For $|V_G| = p$ we call δ_G *symmetric* if

$$\delta(i) + \delta(p-i+1) = \delta(p) \quad \text{for } i = 1, \dots, p.$$

For example, the δ -sequence of the 3-dimensional unit cube $\delta_{Q^3} = (0, 1, 1, 2, 1, 2, 2, 3)$ is symmetric. It is easily shown that if G is regular then δ_G is symmetric. The recent result shows that the converse is also true.

Theorem 2 (Bonnet, Sikora [5]) *If δ_G is symmetric then G is regular.*

Our experience shows that in order for the lexicographic order to be optimal for $G \times G$, the graph G has to be dense, that is, have many edges. It seems that high density and regularity are crucial conditions for the lexicographic order to be optimal. Cliques have highest density and the lexicographic order is optimal for every their Cartesian power [9]. It is interesting to mention that removal of an edge from a clique leads to the next best choice for a high density graph, but products of this graph do not admit any optimal order. A natural way to construct dense regular graphs is to start with a clique K_p (or $K_{p,p}$) and remove a factor from it. In particular, one can consider removing $s \geq 1$ disjoint perfect matchings M from K_p or $K_{p,p}$. These are exactly the graphs being studied in [1, 3, 8, 9]. The δ -sequences of these graphs are as follows:

- $\delta_{K_p} = (\{0, 1, 2, 3, \dots, p-1\})$
- $\delta_{K_p-sM} = (\{0, 1, 2, \dots, \frac{p}{2}-1\}, \{\frac{p}{2}-s, \frac{p}{2}-s+1, \frac{p}{2}-s+2, \dots, p-s-1\})$
- $\delta_{K_{p,p}} = (\{0, 1\}, \{1, 2\}, \{2, 3\}, \dots, \{p-1, p\})$

The braces above show partitioning of δ -sequences into maximum monotonic subsequences. Thus, K_p has just one monotonic subsequence, $K_p - sM$ (a clique with s disjoint perfect matchings removed) has 2 (maximum) monotonic subsequences, and $K_{p,p}$ has p ones. Our main result generalizes all the above mentioned results for graphs $H_{s,p,i}$ defined by their δ -sequences. Namely, $\delta_{H_{s,p,i}}$ must admit partitioning into s monotonic subsequences of size p of the form:

$$(\{0, 1, \dots, p-1\}, \{p-i, \dots, p-i+(p-1)\}, \dots, \{(s-1)(p-i), \dots, (s-1)(p-i)+p-1\}).$$

For example, for $s = 3$, $p = 4$, $i = 2$ one has $\delta_{H_{3,4,2}} = (\{0, 1, 2, 3\}, \{2, 3, 4, 5\}, \{4, 5, 6, 7\})$.

In the next section we present a construction of some graphs $H_{s,p,i}$ with such δ -sequences. Our main result is as follows:

Theorem 3 (Main result) *Lexicographic order is optimal for $H_{s,p,i} \times H_{s,p,i}$ for $p \geq 3$, $s \geq 2$, and $1 \leq i \leq p - i$.*

Due to Theorem 1 this result is also valid for $H_{s,p,i}^n$ for $n \geq 2$. Note that the family of graphs $H_{s,p,i}^n$ include cliques, cliques without s perfect matchings, and also t -partite graphs $K_{p,\dots,p}$. Thus, the only published family of regular graphs that admit optimal orders for all their Cartesian powers and that are not covered by our main result are complete bipartite graphs with s perfect matchings removed [3].

The paper is organized as follows. In the next section we present a general construction of regular graphs admitting optimal orders and show that the graphs $H_{s,p,i}$ for some values of parameters can be constructed this way. In Section 3 we explore some properties of graphs $H_{s,p,i}$ and present some auxiliary results used in the proof of our main result in Section 4. Some computational experiments and concluding remarks are outlined in Section 5.

2 Clique structure of optimal orders

Throughout this section we assume that $G = (V, E)$ is a graph admitting an optimal order. We start with some basic properties of the δ -sequence for a graph $G = (V, E)$. Obviously, $\delta_G(i) \geq 0$ for all $i \in \{1, \dots, |V|\}$. Moreover the strict inequality for $i \geq 2$ holds iff G is connected.

Lemma 1 *Let $G = (V, E)$ be a graph that admits nested solutions. Then $\delta_G(i+1) - \delta_G(i) \leq 1$ for all $i \in \{1, \dots, |V|\}$.*

Proof.

Assume to the contrary that there exists j , $1 \leq j \leq |V|$, such that $\delta(j+1) - \delta(j) > 1$, that is, $\delta_G(j+1) \geq \delta_G(j) + 2$. Let x_1 and x_2 be the j -th and $j+1$ -th vertices in the optimal order \mathcal{O} of G and X be the set of vertices preceding x_1 in this order. Then $|I(X, \{x_1\})| = \delta(j)$. Since $\delta_G(j+1) \geq \delta_G(j) + 2$ we have $|I_G(X, \{x_2\})| = \delta_G(j+1) \geq \delta_G(j) + 1$. Hence, $|I_G(X \cup \{x_2\})| > |I_G(X \cup \{x_1\})|$, which contradicts the optimality of order \mathcal{O} . \square

We call a subsequence of consecutive entries $\delta(a), \dots, \delta(b)$ of δ_G *monotonic segment* if $\delta(a) < \dots < \delta(b)$ and it is longest with respect to this property. This way δ_G can be partitioned into monotonic segments. Denote by $M_{G,i}$ the set of vertices corresponding to the entries of the i -th monotonic segment. We call $M_{G,i}$ the *i -th monotonic set*.

Theorem 4 *Let $G = (V, E)$ admit nested solutions and $M_{G,i}$ be the i^{th} monotonic set corresponding to the monotonic segment $\delta(a), \dots, \delta(b)$. Denote $X = \cup_{s=1}^{i-1} M_{G,s}$. Then $M_{G,i}$ induces a clique in G and $\forall u \in M_{G,i}$ it holds $|I_G(X, \{u\})| = \delta(a)$.*

Proof.

Let $V = \{v_1, v_2, \dots, v_{|V|}\}$, where the vertices are labeled according to an optimal order for G . Denote $S_k = \{v_j \in M_{G,i} \mid j \leq a+k\}$. We prove the theorem by induction on k .

For $k = 0$ the set $S_1 = \{v_a\}$ obviously induces a clique. Moreover, $|I(X, S_1)| = \delta(a)$. Assume that $k \geq 1$ and that the theorem is true for all $k' < k$.

Since $\delta(a), \dots, \delta(b)$ is a monotonic segment, one has $\delta(a+k) = \delta(a) + k$. If S_k is not a clique then $|I_G(S_k, \{v_{a+k}\})| < k - 1$, which implies $|I_G(X, \{v_{a+k}\})| \geq \delta(a) + 1 > |I_G(X, \{v_a\})|$. This,

in turn, implies $|I_G(X \cup \{v_{a+k}\})| > |I_G(X \cup \{v_a\})|$ which contradicts the optimality of the vertex order. \square

The following observation will be used in the proof of Theorem 5.

Remark 1 *If $M_{G,i}$ and $M_{G,j}$ are monotonic sets with $i < j$ and $X \subseteq \cup_{s=1}^{i-1} M_{G,s}$, then for any $u \in M_{G,i}$ and $v \in M_{G,j}$ it holds $|I_G(X, \{u\})| \geq |I_G(X, \{v\})|$.*

For graphs $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ admitting optimal orders denote by $G_1 \circ G_2$ the composition of G_1 and G_2 . That is, the graph $H = (V_H, E_H)$ with

$$\begin{aligned} V_H &= V_1 \cup V_2, \\ E_H &= E_1 \cup E_2 \cup \{(a, b) \mid a \in V_1 \text{ and } b \in V_2\}. \end{aligned}$$

Assuming G admits an optimal order \mathcal{O} , denote by $\mathcal{F}_G(i)$ the set of the first i vertices of V_G in the order \mathcal{O} . Further denote by $P_{G,i} = (V_i, E_i)$ the subgraph of G induced by the vertex set $\mathcal{F}_G(i)$. We call $P_{G,i}$ the i -th partial of G . It is easily seen that the order \mathcal{O} is optimal for $P_{G,i}$ for $i = 1, \dots, |V_G|$. Denote by $\mathcal{P}_G = \{P_{G,i} \mid 0 \leq i \leq |V|\}$ the set of all partials of G . The next theorem presents a general construction of graphs admitting an optimal order. This construction will be then used to construct graphs $H_{s,p,i}$.

Theorem 5 *Let a graph G admit nested solutions and $H_1, H_2, \dots, H_n \in \mathcal{P}_G$ with $H_i = (V_i, E_i)$ and $|V_1| \geq |V_2| \geq \dots \geq |V_n| > 0$. Further let $\{M_{H_i,s}\}$, be the set of monotonic sets of H_i and the vertices of each H_i be ordered in its optimal order \mathcal{O}_i . Then the following order \mathcal{O} is optimal for $S_n = H_1 \circ \dots \circ H_n$: for $u \in M_{H_i,s}$ and $v \in M_{H_j,t}$ we write $u <_{\mathcal{O}} v$ iff*

- (i) $s < t$, or
- (ii) $s = t$ and $i < j$, or
- (iii) $s = t$, $i = j$ and $u <_{\mathcal{O}_i} v$

Proof.

We prove the theorem by induction on n . For $n = 1$ it is obviously true. Assume $n \geq 2$ and that the theorem is true for all $n' < n$.

Let $H_1 \circ \dots \circ H_n = (V, E)$ and $A \subset V$. Denote $U = V_n \cap A$ and $D = V_{S_{n-1}} \cap A$. We transform A by replacing U with $U' = \mathcal{F}_{H_n}(|U|)$ and D with $D' = \mathcal{F}_{S_{n-1}}(|D|)$. Denote the resulting set by B . Since $|I_{S_{n-1}}(D')| \geq |I_{S_{n-1}}(D)|$ and $|I_{H_n}(U')| \geq |I_{H_n}(U)|$ by induction, taking into account that every vertex of S_{n-1} is connected to all vertices of V_n , we conclude $|I_{S_n}(B)| - |I_{S_n}(A)| \geq 0$.

Let $M_{H_n,q}$ be the first monotonic set such that $|U' \cap M_{H_n,q}| < |M_{H_n,q}|$ and let $M_{H_p,w}$ be the last monotonic set such that $D' \cap M_{H_p,w} \neq \emptyset$.

Case 1: Assume $q = w$. Theorem 4 implies that the set $T = \cup_{1 \leq i \leq n} M_{H_i,q}$ is a clique in S_n . Since $I_{S_n}(\cup_{j < q} M_{H_i,j}, \{x\})$ is the same for every i and $x \in M_{H_i,q}$, the number of inner edges of S_n will not change if we replace in $T \cap B$ with any subset of T of the same size. Hence, we can transform B into initial segment of order \mathcal{O} without decreasing the number of its inner edges.

Case 2: Assume $q < w$, as argument in the case $q > w$ is similar. Let $a \in M_{H_n,q} \setminus B$ and $b \in M_{H_p,w} \cap B$ for some p . We transform B to the set $C = (B \setminus \{b\}) \cup \{a\}$. Denote $B_1 = \cup_{i=1}^{q-1} M_{H_n,i}$ and $B_2 = \cup_{i=1}^{q-1} M_{H_p,i}$. By Remark 1 we have $|I_{S_n}(B_1, \{a\})| \geq |I_{S_n}(B_2, \{b\})|$. Since $|B_1| = |B_2|$ we have $|I_{S_n}(B_1, \{b\})| = |I_{S_n}(B_2, \{a\})|$. Denote $B_3 = \cup_{s=q}^w M_{H_p,s}$. Since a is connected to all vertices of S_{n-1} we have $|I_{S_n}(B_3 \cap C, \{b\})| \leq |I_{S_n}(B_3 \cap C, \{a\})|$. Since $M_{H_n,q}$ is a clique and b is connected to all vertices of H_n we have $|I(M_{H_n,q} \cap B, \{a\})| = |I(M_{H_n,q} \cap B, \{b\})|$. Since a and b are connected

to all vertices of $S_n \setminus (H_n \cup H_p)$ we have $|I_{S_n}(B \setminus (H_n \cup H_p), \{a\})| = |I_{S_n}(B \setminus (H_n \cup H_p), \{b\})|$. Hence, $|I_{S_n}(C)| \geq |I_{S_n}(B)|$. This way we can keep moving vertices one by one until we get an initial segment of order \mathcal{O} . \square

As an immediate application of this result we provide a construction for the graphs $H_{s,p,i}$ for some sets of parameters.

Theorem 6 *Let $p \in N$ and F be the set of all factors of p . Then $H_{s,p,i}$ exists for every $i \in F$.*

Proof.

Let $i \in F$ and $G = (V, E)$ be a disjoint union of s cliques, each of size i . It is easily shown that $\delta(G) = (\{0, 1, \dots, i-1\}, \{0, 1, \dots, i-1\}, \dots, \{0, 1, \dots, i-1\})$, where the sequence in braces repeats i times.

Theorem 5 implies that the composition $H = G \circ \dots \circ G$ (p/i times) admits nested solutions. Taking into account the optimal order for H stated in the theorem, we conclude $\delta_H = \delta_{H_{s,p,i}}$. \square

3 Some auxiliary results

Let $G = (V, E)$ be a graph admitting an optimal order. We label its vertices with $0, 1, \dots, |V| - 1$ according to that order. For $A \subseteq V^2$ denote $A_i(a) = \{(x_1, x_2) \in A \mid x_i = a\}$. We say that A is *compressed* if $A_i(a) = \{0, 1, \dots, |A_i(a)| - 1\}$ for $i = 1, 2$ and any $a \in V$. It is known (see, e.g. [2]) that if G admits an optimal order then there exist compressed optimal sets of $V_G \times V_G$. If $A \subseteq V^2$ is compressed then

$$|I(A)| = \sum_{(x,y) \in A} (\delta_G(x) + \delta_G(y)). \quad (1)$$

In this and next section we assume V is the vertex set of $H_{s,p,i}$ and view the vertices of $V \times V$ as being placed in a matrix M_{V^2} . The columns and rows of this matrix represent the vertices of V ordered in its optimal order from left to right and from bottom to top. A set of vertices of M_{V^2} is called *downset* if the corresponding set of $V \times V$ is compressed.

We associate a weight with every vertex $(x, y) \in M_{V^2}$ defined by $w(x, y) = \delta_{H_{s,p,i}}(x) + \delta_{H_{s,p,i}}(y)$ and for a set $Z \subseteq M_{V^2}$ define $w(Z) = \sum_{(x,y) \in Z} w(x, y)$. This way we can consider a slightly more general problem than EIP: for a given m find an m -element downset of M_{V^2} with maximum weight. It is easily seen that the weight of a maximum weight downset is equal to $I_{H_{s,p,i}}(m)$ if the graph $H_{s,p,i}$ with the corresponding δ -sequence exists. However, we abstract from existence of the graph and will be dealing with maximization of the function $I(\cdot)$ defined by (1) for compressed sets even if the graph $H_{s,p,i}$ does not exist, assuming in this case that we actually maximize the weight of a downset of M_{V^2} . This way we prove a minor extension of Theorem 3 for maximum weight downsets of M_{V^2} .

For $A, B \subseteq V^2$ such that B and $B \cup A$ are compressed and $A \cap B = \emptyset$ denote

$$d(A) = |I(B \cup A) \setminus I(B)|.$$

Lemma 2 *If $(x, y) \in V^2$ and $(x, y + qp) \in V^2$ then*

$$d(\{(x, y + qp)\}) - d(\{(x, y)\}) = q(p - i)$$

Proof.

Denote $t = \lfloor y/p \rfloor$. It can be easily shown that

$$\begin{aligned} d(\{(x, y)\}) &= (y \bmod p) + t(p - i). \\ d(\{(x, y + qp)\}) &= ((y + qp) \bmod p) + (t + q)(p - i). \end{aligned}$$

Hence, we have

$$\begin{aligned} d(\{(x, y + qp)\}) - d(\{(x, y)\}) &= ((y + qp) \bmod p) + (t + q)(p - i) - (y \bmod p) - t(p - i) \\ &= q(p - i). \end{aligned}$$

□

Lemma 3 *Let $A_1, A_2 \subseteq V^2$ such that*

$$\begin{aligned} A_1 &= \{(x, y) \mid x = a \text{ and } b \leq y < b + p \text{ for some } a, b\} \\ A_2 &= \{(x, y + q) \mid (x, y) \in A_1\} \end{aligned}$$

one has $d(A_2) - d(A_1) = q(p - i)$.

Proof.

In other words, A_1 is a subset of consecutive vertices in a column of M_{V^2} and A_2 is a shift of A_1 on q rows up.

We prove the lemma by induction on q . For $q = 1$ Lemma 2 implies

$$\begin{aligned} d(A_2) - d(A_1) &= d(\{(x, y + p)\}) - d(\{(x, y)\}) \\ &= p - i. \end{aligned}$$

Assume the statement holds for all $q' \leq q$. By induction we have

$$\begin{aligned} d(A_2) - d(A_1) &= q(p - i) + d(\{(x, y + q)\}) - d(\{(x, y + q + p)\}) \\ &= q(p - i) + p - i \\ &= (q + 1)(p - i) \end{aligned}$$

□

Lemma 4 *Let $A_1, A_2 \subseteq V^2$ such that*

$$\begin{aligned} A_1 &= \{(x, y) \mid u \leq x < u + p \text{ for some } u \geq y \text{ and fixed } y\} \\ A_2 &= \{(y + r, x - d) \mid (x, y) \in A_1 \text{ for some } 0 \leq r < \lceil x/p \rceil p - x\}. \end{aligned}$$

Then $d(A_2) - d(A_1) = rp - d(p - i)$.

Proof.

The condition $u \geq y$ provides that A_1 is below the main diagonal of M_{V^2} . Let R be the *reflections* of A_1 about the main diagonal and S be its *shift down* on d rows. Formally,

$$\begin{aligned} R &= \{(y, x) \mid (x, y) \in A_1\}, \\ S &= \{(x, y - d) \mid (x, y) \in R\}. \end{aligned}$$

Then A_2 is a *horizontal shift* of S right on r columns. We have $d(R) - d(A_1) = 0$ and $d(R) - d(S) = d(p - i)$ by Lemma 3. Moreover, $d(A_2) - d(S) = rp$. Therefore,

$$\begin{aligned} d(A_2) - d(A_1) &= d(A_2) - d(S) + d(S) - d(R) \\ &= d(A_2) - d(S) - (d(R) - d(S)) \\ &= rp - d(p - i). \end{aligned}$$

□

Lemma 5 For a fixed $a \geq 1$ and sets $A = \{(x, y) \mid x = a\} \subseteq V^2$ and $B = \{(x - 1, y) \mid (x, y) \in A\}$ one has $d(B) - d(A) \geq -|B| = -|A|$.

Proof.

If $a \not\equiv 0 \pmod p$ then

$$d(B) - d(A) = -|B| = -|A|.$$

Otherwise, if $a = wp$ for some $w \in \{1, \dots, s - 1\}$ then

$$\begin{aligned} d(B) - d(A) &= |B|(p - 1 + (w - 1)(p - i)) - |B|w(p - i) \\ &= |B|(p - 1 - p + i) \\ &= |B|(i - 1) \\ &\geq 0. \end{aligned}$$

So we have $d(B) - d(A) \geq -|B| = -|A|$ as desired. \square

Theorem 7 (Bezrukov, Elsässer [3]) *If $p \geq 3$ and $1 \leq i \leq p - i$ then the lexicographic order is optimal for $H_{2,p,i}^2$.*

We use Theorem 7 and some parts of its proof in the proof of our main result.

Lemma 6 (see, e.g., [3]) *Let $G = (V_G, E_G)$ be a regular graph and $A \subseteq V_G$. Then A is an optimal set iff $\overline{A} = V_G \setminus A$ is optimal.*

This lemma implies that that regardless which i perfect matchings are removed from K_{2p} to obtain $H_{2,p,i}$, the resulting graph admits an optimal order. Note that Theorem 7 in [3] deals with a specific removal of i perfect matchings. However, it remains valid for removal of any i disjoint perfect matchings.

4 Proof of Theorem 3

Let $V = V_{H_{s,p,i}}$ and $A \subseteq V^2$ be a compressed set. We also assume that A is stable under reflection about the main diagonal of M_{V^2} . That is, the condition $(x, y) \in A$ implies $(y, x) \in A$. For $1 \leq k, l \leq s$ and $A \subseteq V^2$ denote

$$\begin{aligned} V_{k,l} &= \{(u, v) \mid (k - 1)p \leq u \leq kp - 1, (l - 1)p \leq v \leq lp - 1\} \\ A_{k,l} &= A \cap V_{k,l} \end{aligned}$$

We prove the theorem by induction on s . The base case $s = 2$ is proved in [3]. Assume $s \geq 3$ and the theorem holds for all $s' < s$.

Case 1. Assume $A \subseteq \bigcup_{k=1}^{s-1} (\bigcup_{l=1}^s V_{k,l})$. Let $A', A'' \subseteq A$ such that $A' = \bigcup_{k=1}^{s-1} (\bigcup_{l=1}^{s-1} V_{k,l})$ and $A'' = \bigcup_{k=1}^{s-1} (\bigcup_{l=2}^s V_{k,l})$. We transform A by replacing A' with $\mathcal{F}_{A'}^2(|A'|)$ and A'' with $\mathcal{F}_{A''}^2(|A''|)$. It is easily seen that the resulting set B will be compressed and optimal. Moreover, the sum of the lexicographic numbers of vertices of B is less than the one for A . Therefore, after a finite number of repetitions of such transformation we obtain a set B which is stable under this transformation. For B denote

$$\begin{aligned} k_1 &= \max_{(q,0) \in B} q, \\ k_2 &= \max_{(q,sp-1) \in B} q + 1, \\ y_1 &= \max_{(k_1,q) \in B} q, \\ y_2 &= \max_{(k_2,q) \in B} q. \end{aligned}$$

Taking into account that B is compressed, we have $k_2 \leq k_1 \leq k_2 + 1$. If $k_1 = k_2$ then $y_1 = y_2$, hence $B = \mathcal{F}_V^2(|B|)$. Therefore, without loss of generality we assume $k_1 = k_2 + 1$ and $y_1 < p$. We have $y_2 \bmod p \geq y_1$. Indeed, if this is not the case then we transform B to C by replacing $B' = \{(k_1, y) \mid y_2 \bmod p < y \leq y_1\} \subseteq B$ with $C' = \{(k_2, y) \mid y_2 < y \leq y_1 + (s-1)p\} \subseteq V^2 \setminus B$. By taking into account Lemma 5 and Lemma 2 we have $|I(C)| - |I(B)| \geq |B'|((s-1)(p-i) - |B'|) = |B'|((s-1)(p-i) - 1) > 0$, which contradicts the optimality of B .

If $y_2 \bmod p \geq y_1$ and $sp - y_2 - 1 > y_1 + 1$ we transform B to D by replacing $B' = \{(k_1, y) \mid 0 \leq y \leq y_1\} \subseteq B$ with $D' = \{(k_2, y) \mid y_2 < y \leq y_2 + y_1 + 1\} \subseteq V^2 \setminus B$. By Lemmas 5 and 2 we have $|I(D)| - |I(B)| > |B'|((s-1)(p-i) - |B'|) = |B'|((s-1)(p-i) - 1) > 0$, which again contradicts the optimality of B .

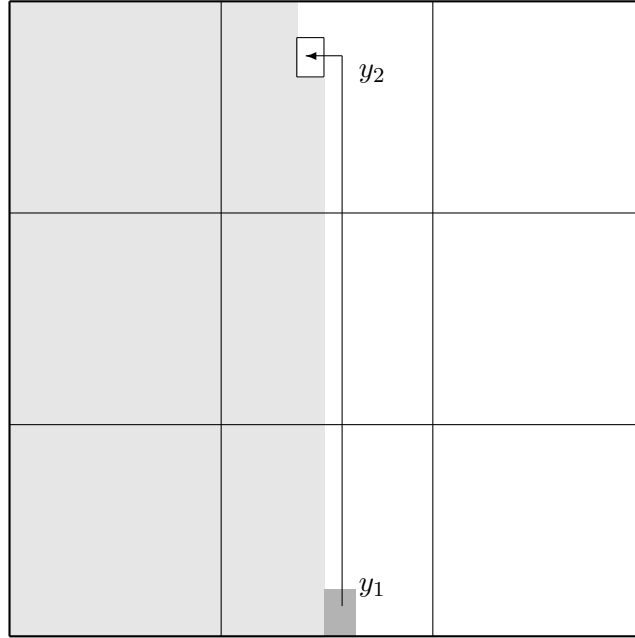


Figure 1: Transforming set B into D in *Case 1*

If $y_2 \bmod p \geq y_1$ and $sp - y_2 - 1 \leq y_1 + 1$ we transform B to H by replacing $B' = \{(k_1, y) \mid y_1 - (sp - y_2 - 1) < y \leq y_1\}$ with $H' = \{(k_2, y) \mid y_2 < y < sp\}$. By Lemmas 5 and 2 we have $|I(H)| - |I(B)| > |B'|((s-1)(p-i) - |B'|) = |B'|((s-1)(p-i) - 1) > 0$, which still contradicts the optimality of B .

Case 2. Assume $A \subseteq V^2$ and $A_{s,1} \neq \emptyset$. Denote

$$\begin{aligned}
 V_h &= \bigcup_{k=1}^{s-1} \left(\bigcup_{l=2}^s V_{k,l} \right), & A_h &= A \cap V_h \\
 V_2 &= \bigcup_{l=2}^s V_{1,l}, & A_2 &= A \cap V_2 \\
 V_3 &= \bigcup_{k=2}^s V_{k,1}, & A_3 &= A \cap V_3.
 \end{aligned}$$

By inductive hypothesis we can assume that A_h is an initial segment in “columns” of V_h , and also A_3 is an initial segment in “rows” of V_3 . Without loss of generality we can assume that

$A_h = A_2$, since otherwise we can apply arguments similar to the one of *Case 1* to further transform the set to $\mathcal{F}_V^2(|A|)$. After given transformation the number of inner edges between $A_{1,1}$ and A_2 and between $A_{1,1}$ and A_3 does not decrease. Let

$$\begin{aligned} |A_2| &= k_2(s-1)p + \gamma_2 \\ |A_3| &= k_3(s-1)p + \gamma_3 \end{aligned}$$

with $0 \leq \gamma_2, \gamma_3 < (s-1)p$. From the arguments above $k_2 < p$. Since A is stable under reflection, we have $k_2 \geq k_3$.

Let $\epsilon = 0$ if $\gamma_3 > 0$ and $\epsilon = 1$ if $\gamma_3 = 0$. Let $V_5 = \{(x, y) \in V_{1,1} | k_2 \leq x < p, k_3 + \epsilon \leq y < p\}$. Replace $A_5 = A \cap V_5$ with the initial segment of V_5 . It is easily seen that the resulting set remains optimal. Let $|A_5| = (p - k_3 - \epsilon)k_5 + \gamma_5$ with $0 \leq \gamma_5 < p - k_3 - \epsilon + 1$.

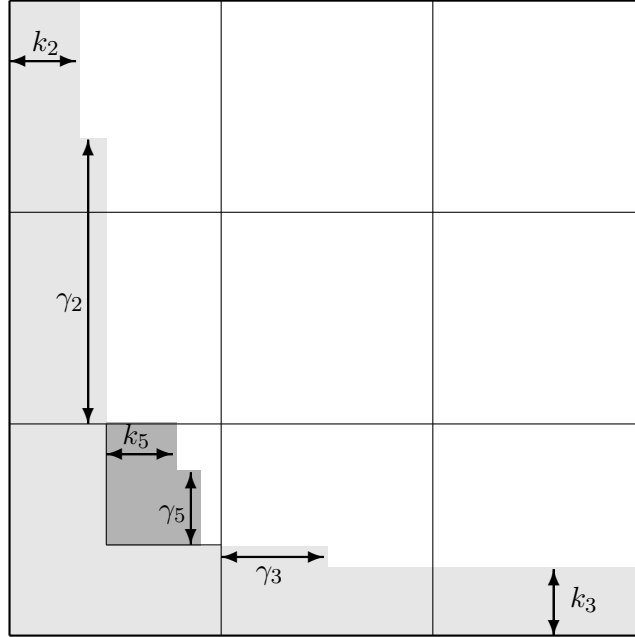


Figure 2: Notations used for *Case 2*

Case 2a. We show that $\gamma_2 = 0$.

If $k_3 > 0$ and $\gamma_3 > 0$, we first exchange the sets $A' = \{(x, 0) | p + \gamma_3 \leq x < sp\}$ and $B' = \{(x, k_3) | (x, 0) \in A'\}$ and transform A to a resulting set B such that $|I(B)| = |I(A)|$. If $k_3 > 0$ and $\gamma_3 = 0$, we transform B to a resulting set C by exchanging $B' = \{(x, k_3 - \epsilon) | p + \gamma_2 \leq x < sp\}$ with $C' = \{(k_2, y) | (y, k_3 - \epsilon) \in B'\}$. Since B' and C' are isomorphic segments in V and $k_2 \geq k_3$ we have that $|I(C)| - |I(B)| > 0$. Hence we have a contradiction with the optimality of C .

If $k_3 = 0$ we have that $\gamma_2 \geq \gamma_3$. If it is not the case then we transform A to D by exchanging $A' = \{(x, 0) | p + \gamma_2 \leq x < p + \gamma_3\}$ with $D' = \{(k_2, y) | (y, 0) \in A'\}$. Since A' and D' represent isomorphic segments in V and $k_2 \geq k_3$ we have that $|I(D)| - |I(A)| \geq 0$. Hence the set D is optimal. So we can assume $\gamma_2 \geq \gamma_3$.

If $k_3 = 0$, $\gamma_2 \geq \gamma_3$, $\gamma_3 > (s-2)p$ and $\gamma_3 - (s-2)p \leq (s-1)p - \gamma_2$ we transform A to resulting set H by replacing $A' = \{(0, b) | (s-1)p \leq a < \gamma_3\}$ with $H' = \{(b, k_2) | \gamma_2 \leq b < p + \gamma_2 + \gamma_3 - (s-2)p\}$. We have $|I(H)| - |I(A)| > k_2(\gamma_3 - (s-2)p) > 0$. Now we can apply arguments of *Case 1* on H .

If $k_3 = 0$, $\gamma_2 \geq \gamma_3$, $\gamma_3 > (s-2)p$ and $\gamma_3 - (s-2)p > (s-1)p - \gamma_2$ we transform A to resulting set K by replacing $A' = \{(0, b) \mid \gamma_3 - ((s-1)p - \gamma_2) \leq a < \gamma_3\}$ with $K' = \{(b, k_2) \mid \gamma_2 \leq b < sp\}$. We have

$$|I(K)| - |I(A)| > ((s-1)p - \gamma_2)k_2 \geq 0.$$

Hence, we have a contradiction with the optimality of A , which implies $\gamma_2 = 0$.

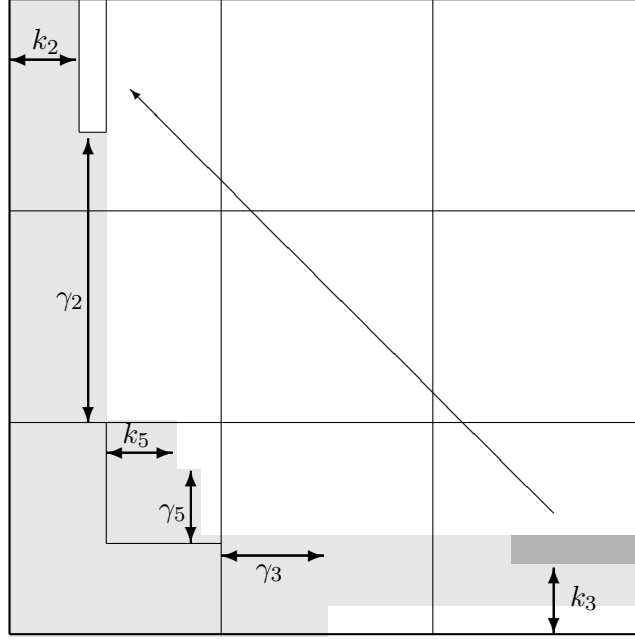


Figure 3: Transforming set A to C in *Case 2a* for $k_3 > 0$

Case 2b. Assume $\gamma_2 = 0$ and $k_5 > 0$. If $k_5 > k_3$ or $k_5 = k_3$ and $\gamma_3 = 0$, then $|A| \leq sp^2$. In this case we move a point (x, y) to $(y + k_2, x)$ for every $(x, y) \in A_3$. Such transformation results in a set $C \subseteq V_2$ and it is easily seen that $|I(C)| \geq |I(A)|$. Moreover, C satisfies conditions of *Case 1*. So we use arguments of *Case 1* to further transform C to $\mathcal{F}_V^2(|A|)$.

If $1 \leq k_5 < k_3$ or $1 \leq k_5 = k_3$ and $\gamma_3 > 0$, we move $(x, y) \in A_3$ to $(y + k_2, x) \in V_2 \setminus A$ for $p \leq x < sp$ and $0 \leq y < k_5$. We show that for the resulting set C we have $|I(C)| - |I(A)| > 0$.

We move $(x, y) \in A_3$ for $(s-1)p \leq x < sp$ and $0 \leq y < k_5$ to $(y + k_2, x) \in V_2 \setminus A$. For the resulting set C , we have,

$$|I(C)| - |I(A)| = k_5(s-1)p(k_2 - (k_3 - k_5)) - \gamma_3 k_5 \geq k_5((s-1)p - \gamma_3) > 0$$

which contradicts the optimality of A .

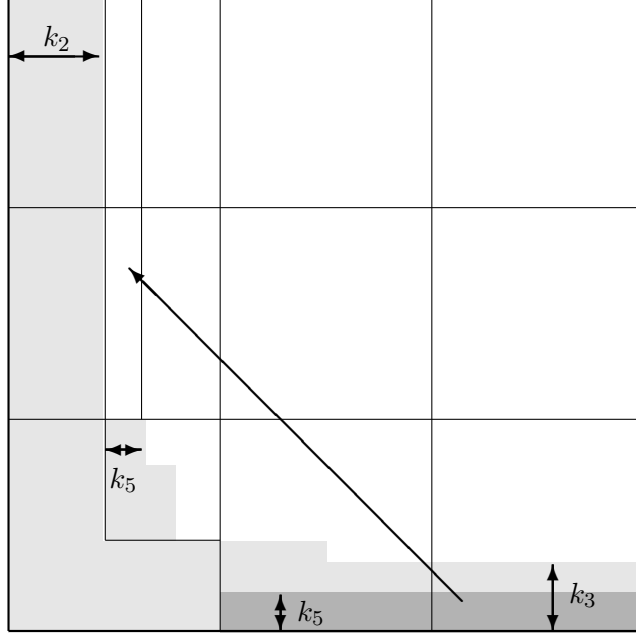


Figure 4: Transforming set A into C in *Case 2b* for $k_5 < k_3$

Case 2c. Assume $\gamma_2 = 0$, $k_5 = 0$, $k_3 > 0$ and $k_2 < p - 1$.

We first transform A to C by replacing the set $C' = \{(k_2, y) \mid k_3 \leq y < k_3 + \gamma_3\}$ with $\{(x + 1, y) \mid (x, y) \in C'\}$ and if $\gamma_3 > 0$, replacing the set $C'' = \{(x, 0) \mid p + \gamma_3 \leq x < sp\}$ with $\{(x, k_3) \mid (x, 0) \in C''\}$. For the resulting set C one has $|I(A)| = |I(C)|$. Denote

$$\begin{aligned}
P &= \{(x, k_3 - \epsilon) \mid k_2 \leq x < sp\}, \\
Q &= \{(k_2, y) \mid k_3 - \epsilon \leq y < k_3 - \epsilon + sp - k_2\} \\
&= \{(k_2, y) \mid k_2 - (k_2 - k_3 + \epsilon) \leq y < sp - (k_2 - k_3 + \epsilon)\} \\
&= \{(x + (k_2 - k_3 + \epsilon), y - (k_2 - k_3 + \epsilon)) \mid (y, x) \in P\}
\end{aligned}$$

Now we further transform C into B by replacing P with Q . We prove by induction on s that $|I(B)| - |I(C)| > 0$. For $s = 2$ this is proved in [3]. Assume $s \geq 3$ and this is true for all $s' < s$.

Since $|P \cap V_{s,1}| = p$ and $s \geq 3$ we have $|P| = |Q| > p$. Let $P' \subseteq P$ be the set of p vertices of P with largest x -coordinates. Similarly, let $Q' \subseteq Q$ be the set of p vertices of Q with largest y -coordinates. Since $|P'| = |Q'| = p$, the x -coordinates of vertices of $P \setminus P'$ and y -coordinates of vertices of $Q \setminus Q'$ do not exceed $(s - 1)p$. By induction on s we have $d(Q \setminus Q') - d(P \setminus P') > 0$. Lemma 4 implies $d(Q') - d(P') = (k_2 - k_3 + \epsilon)p - (k_2 - k_3 + \epsilon)(p - i)$. Hence,

$$\begin{aligned}
|I(B)| - |I(C)| &\geq d(Q) - d(P) \\
&= d(Q \setminus Q') + d(Q') - (d(P \setminus P') + d(P')) \\
&= d(Q \setminus Q') - d(P \setminus P') + (k_2 - k_3 + \epsilon)p - (k_2 - k_3 + \epsilon)(p - i) \\
&> (k_2 - k_3 + \epsilon)p - (k_2 - k_3 + \epsilon)(p - i) \\
&= (k_2 - k_3 + \epsilon)i \\
&\geq 0
\end{aligned}$$

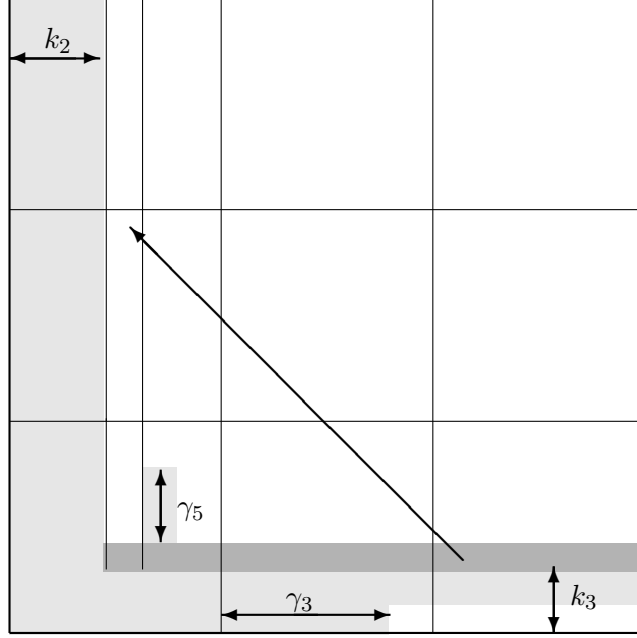


Figure 5: Transforming set C into B in *Case 2c*

Case 2d. Assume $\gamma_2 = 0$, $k_5 = 0$, $k_3 > 0$ and $k_2 = p - 1$. If $\gamma_3 > 0$ we first transform A to C by replacing the set $C' = \{(x, 0) \mid p + \gamma_3 \leq x < sp\}$ with $\{(x, k_3) \mid (x, 0) \in C'\}$. For the resulting set C one has $|I(A)| = |I(C)|$, so C is optimal. Denote

$$\begin{aligned}
P &= \{(x, k_3 - \epsilon) \mid p \leq x < sp\}, \\
Q &= \{(p - 1, y) \mid k_3 - \epsilon + \gamma_5 + 1 \leq y < sp - p + k_3 - \epsilon + \gamma_5 + 1\} \\
&= \{(p - 1, y) \mid p - (p - 1 - k_3 + \epsilon - \gamma_5) \leq y < sp - (p - 1 - k_3 + \epsilon - \gamma_5)\} \\
&= \{(x + (p - 1 - k_3 + \epsilon), y - (p - 1 - k_3 + \epsilon - \gamma_5)) \mid (y, x) \in P\}.
\end{aligned}$$

Let $B = (C \setminus P) \cup Q$. We prove by induction on s that $|I(B)| - |I(C)| > 0$. For $s = 2$ this is proved in [3]. Assume $s \geq 3$ and this is true for all $s' < s$.

Since $|P \cap V_{s,1}| = p$ and $s \geq 3$ we have $|P| = |Q| > p$. Let $P' \subseteq P$ be the set of p vertices of P with largest x -coordinates. Similarly, let $Q' \subseteq Q$ be the set of p vertices of Q with largest y -coordinates. Since $|P'| = |Q'| = p$, the x -coordinates of vertices of $P \setminus P'$ and y -coordinates of vertices of $Q \setminus Q'$ do not exceed $(s - 1)p$. By induction on s we have $d(Q \setminus Q') - d(P \setminus P') > 0$. Lemma 4 implies $d(Q') - d(P') = (p - 1 - k_3 + \epsilon)p - (p - 1 - k_3 + \epsilon - \gamma_5)(p - i)$. Hence,

$$\begin{aligned}
|I(B)| - |I(C)| &\geq d(Q) - d(P) \\
&= d(Q \setminus Q') + d(Q') - (d(P \setminus P') + d(P')) \\
&= d(Q \setminus Q') - d((P \setminus P')) + (p - 1 - k_3 + \epsilon)p - (p - 1 - k_3 + \epsilon - \gamma_5)(p - i) \\
&> (p - 1 - k_3 + \epsilon)p - (p - 1 - k_3 + \epsilon - \gamma_5)(p - i) \\
&> \gamma_5(p - i) \\
&\geq 0.
\end{aligned}$$

Therefore, $|I(B)| - |I(C)| > 0$ for all s , which, in turn, contradicts the optimality of A .

Case 2e. Assume $\gamma_2 = 0$, $k_5 = 0$ and $k_3 = 0$. We can assume that $\gamma_3 > (s - 2)p$, since if this is not the case we can use arguments of *Case 1* to transform A into $\mathcal{F}_V^2(|A|)$.

If $\gamma_5 \geq k_2$ then we transform A into a set B by replacing $B' = \{(x, 0) \mid \gamma_5 + 1 \leq x < p + \gamma_3\}$ with $B'' = \{(k_2, y) \mid (y, 0) \in B'\}$. Since B' and B'' represent isomorphic segment in V and $k_2 \geq k_3$ we have that $|I(B)| - |I(A)| \geq 0$. Now we can use arguments of *Case 1* to transform A into $\mathcal{F}_V^2(|A|)$.

Case 2f. Assume $\gamma_2 = 0$, $k_5 = 0$, $k_3 = 0$, $\gamma_3 > (s - 2)p$ and $\gamma_5 < k_2$. Denote

$$\begin{aligned} P &= \{(x, 0) \mid k_2 + 1 \leq x < p + \gamma_3\} \\ Q &= \{(k_2, y) \mid \gamma_5 + 1 \leq y < \gamma_5 + 1 + p + \gamma_3 - k_2 - 1\} \\ &= \{(k_2, y) \mid k_2 + 1 - (k_2 - \gamma_5) \leq y < p + \gamma_3 - (k_2 - \gamma_5)\} \\ &= \{(x + k_2, y - (k_2 - \gamma_5)) \mid (y, x) \in P\}. \end{aligned}$$

Let $B = (A \setminus P) \cup Q$. We prove by induction on s that $|I(B)| - |I(A)| > 0$. For $s = 2$ this is proved in [3]. Assume $s \geq 3$ and this is true for all $s' < s$.

Since $\gamma_3 > (s - 2)p$ and $s \geq 3$ we have $|P| = |Q| > p$. Let $P' \subseteq P$ be the set of p vertices of P with largest x -coordinates. Similarly, let $Q' \subseteq Q$ be the set of p vertices of Q with largest y -coordinates. Since $|P'| = |Q'| = p$, the x -coordinates of vertices of $P \setminus P'$ and y -coordinates of vertices of $Q \setminus Q'$ do not exceed $(s - 1)p$. By induction on s we have $d(Q \setminus Q') - d(P \setminus P') > 0$. Lemma 4 implies $d(Q') - d(P') = k_2p - (k_2 - \gamma_5)(p - i)$. One has

$$\begin{aligned} |I(B)| - |I(A)| &\geq d(Q) - d(P) \\ &= d(Q \setminus Q') + d(Q') - (d(P \setminus P') + d(P')) \\ &= d(Q \setminus Q') - d((P \setminus P')) + k_2p - (k_2 - \gamma_5)(p - i) \\ &> k_2p - (k_2 - \gamma_5)(p - i) \\ &> \gamma_5(p - i) \\ &\geq 0 \end{aligned}$$

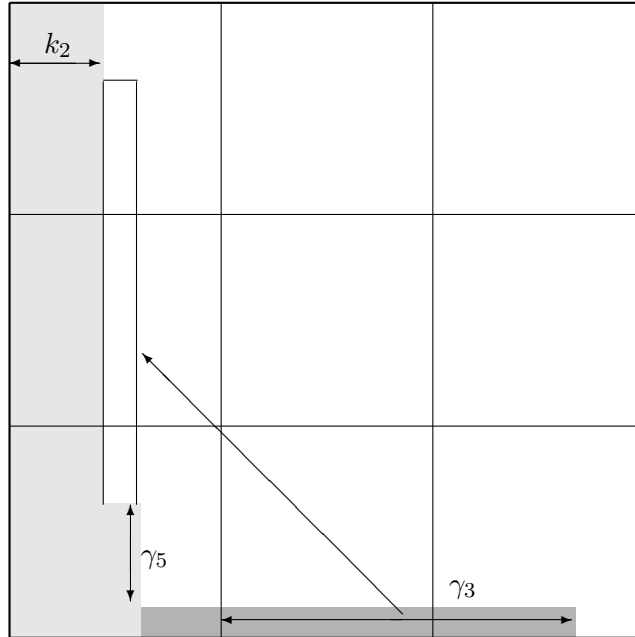


Figure 6: Transforming set A into B in *Case 2f*

Hence, $|I(B)| - |I(A)| > 0$ and we have a contradiction with the optimality of A for all s .

Case 3. Assume $A \subset V^2$ and $A_{2,s} \neq \emptyset$. Hence, $A_{s,2} \neq \emptyset$. Let $\bar{A} = V^2 \setminus A$. We transform \bar{A} by replacing every $(x, y) \in A$ with $(sp - x, sp - y)$. By Lemma 6 the obtained set B is optimal iff A is optimal. Moreover, B is compressed and satisfies conditions of *Case 1* or *Case 2*. Hence we can apply arguments from those cases to transform B to $\mathcal{F}_V^2(|B|)$ without decreasing the number of its inner edges. \square

5 Further results and concluding remarks

Counterexamples show that not for every δ -sequence there is a corresponding graph (V, E) [2]. A necessary (but not sufficient) condition for the graph existence is $\delta(i+1) \leq \delta(i) + 1$ for $1 \leq i < |V|$. For a graph to be connected it must hold $\delta(i) > 0$ for $i > 1$. We call δ -sequences satisfying these two conditions *appropriate*.

How typical is that the lexicographic order is optimal for the products of regular graphs? To answer this question we generated all appropriate symmetric δ -sequences of small length $|V|$ and verified the corresponding graphs G (if exist) for the optimality on $G \times G$ [7]. We call δ_G *isoperimetric* if $G \times G$ admits some optimal order.

It turns out that the lexicographic order is optimal for all of the explored δ -sequences with an exclusion of the Petersen graph. At the same time we identified new graphs that admit optimal orders for all their Cartesian powers (due to the local-global principle [1]). Graphs marked with an asterisk in the tables below were not previously studied. There are no any new graphs for $n \leq 8$.

For $n = 9$ there are 10 symmetric appropriate δ -sequences, out of which only 5 are isoperimetric.

δ -sequence	graph
(0, 1, 1, 2, 2, 2, 3, 3, 4)	interesting new graph*
(0, 1, 2, 1, 2, 3, 2, 3, 4)	$K_3 \times K_3$ or $K_9 - 2C_9^*$ or $K_9 - (K_3 \times K_3)^*$
(0, 1, 2, 2, 3, 4, 4, 5, 6)	$K_{3,3,3}$ or $K_9 - 3C_3^*$
(0, 1, 2, 3, 3, 3, 4, 5, 6)	$K_9 - C_9^*$
(0, 1, 2, 3, 4, 5, 6, 7, 8)	K_9

Table 1: Symmetric isoperimetric sequences of length 9

For $n = 10$ there are 36 symmetric δ -sequences, out of which only 11 are isoperimetric. However, only one of them leads to a graph which was not studied before.

For $n = 11$ there are 28 symmetric δ -sequences, out of which only 5 are isoperimetric.

In [3] we constructed dense regular graphs G admitting optimal orders for $G \times G$ by removing some perfect matchings from K_p or $K_{p,p}$. This way $|V_G|$ must be even. To avoid this restriction we attempted to remove 2-factors from K_p . It turns out that for the resulting graph to admit some optimal order on $G \times G$ it is important which 2-factor to remove. However, in the simplest setting, how about removing a Hamiltonian cycle from K_p ? Particularly interesting is the case of odd p , which is not covered by [3]. This way we came to the graph $K_p - C_p$ with

$$\delta_{K_p - C_p} = (\{0, 1, 2, \dots, (p-3)/2\}, \{(p-3)/3\}, \{(p-3)/2, \dots, p-3\}).$$

This type of δ -sequence has a ‘‘plateau’’ in the middle and is not covered by Theorem 3. However,

Theorem 8 (DeVries [7]) *Lexicographic order is optimal for $(K_p - C_p)^2$ for odd $p \geq 9$ or $p = 5$.*

It is interesting to mention that $(K_7 - C_7)^2$ does not admit any optimal order.

δ -sequence	graph
(0, 1, 1, 1, 2, 1, 2, 2, 2, 3)	Petersen graph
(0, 1, 1, 2, 1, 2, 1, 2, 2, 3)	$C_5 \times P_1$
(0, 1, 1, 2, 2, 2, 2, 3, 3, 4)	$K_{5,5} - M$
(0, 1, 1, 2, 2, 3, 3, 4, 4, 5)	$K_{5,5}$
(0, 1, 2, 2, 2, 3, 3, 3, 4, 5)	$K_{10} - 4M$
(0, 1, 2, 2, 3, 3, 4, 4, 5, 6)	$K_{10} - 3M$
(0, 1, 2, 3, 3, 4, 4, 5, 6, 7)	$K_{10} - 2C_5^*$
(0, 1, 2, 3, 4, 1, 2, 3, 4, 5)	$K_5 \times K_1$
(0, 1, 2, 3, 4, 3, 4, 5, 6, 7)	$K_{10} - 2M$
(0, 1, 2, 3, 4, 4, 5, 6, 7, 8)	$K_{10} - M$
(0, 1, 2, 3, 4, 5, 6, 7, 8, 9)	K_{10}

Table 2: Symmetric isoperimetric sequences of length 10

δ -sequence	graph
(0, 1, 2, 2, 2, 3, 4, 4, 4, 5, 6)	$K_{11} - 2C_{11}^*$
(0, 1, 2, 2, 3, 3, 3, 4, 4, 5, 6)	previously unknown*
(0, 1, 2, 3, 3, 4, 5, 5, 6, 7, 8)	previously unknown*
(0, 1, 2, 3, 4, 4, 4, 5, 6, 7, 8)	$K_{11} - C_{11}^*$
(0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10)	K_{11}

Table 3: Symmetric isoperimetric sequences of length 11

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